#### ISO9001:2015 C€

### Performing End of The Robot Pneumatic Fingers

### Performing End of The Robot Pneumatic Fingers



### Features

- 1. The jaw part adopts powder metallurgy technology, it is not easy to break, it has high toughness and high strength.
- The high rigidity and precision linear guide rail is used in the integral structure design.
- The bottom of the linear guide rail with a positioning pin to prevent the track and the body offset.
- 4. Open and close stroke has a standard type and long stroke type.



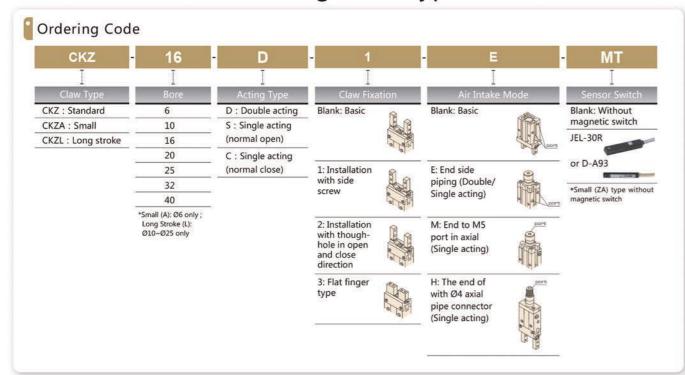




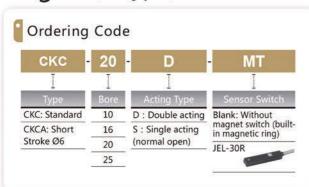
CKZ Series CKC Series

**CKY Series** 

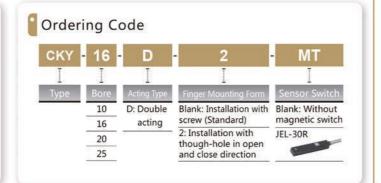
## CKZ Series Pneumatic Fingers (H type)



## CKC Series Pneumatic Fingers (Y Type)



## CKY Series Pneumatic Fingers (180°)



#### Cylinder Cylinder Calculation Calculation SI A. SIB SIB SQ SQ DNT DNT SC / SU SCT SCT SC A. SC A. SL DN DN DSN DSN DN/DSN A. DN/DSN A. MA MA MAC MAC MA/MACA. MA/MAC A. MAL MAL MALC MALC MAL/MACL A. MAL/MACL A. SDA SDA CQ2 CQ2 TCQ2 TCQ2 ADN ADN TADN TADN PPRM PPRM MHL2 MHL2 MXH/MXQ MXH/MXO

CJP

CJ2

CDU

TN

CXS

MGP

MSQ

CJP

CJ2

CDU

TN

CXS

MGP

MSQ

# OJELPC' CKS2-32D





CKS2 Series

CKS3 Series

CKS4 Series

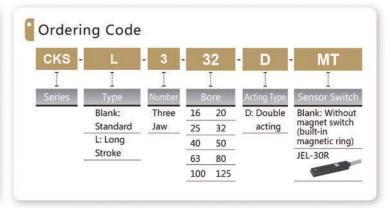
#### **Features**

- Internal use of the wedge structure, get a larger clamping force.
- The front end of the piston is provided with the design of collision proof, which can effectively reduce the metal impact sound when the jaw is released.
- Clamp with high precision repeat, convenience for the installation of the animation device.
- A variety of series of pneumatic finger for customers to choose, the clamping of various forms of work material.

## CKS2 Series Pneumatic Finger (Two Jaw)

## 

## CKS3 Series Pneumatic Finger (Three Jaw)



## CKS4 Series Pneumatic Finger (Four Jaw)

